

# **Key features**

- Configurable receiver, scalable for future requirements.
- Available in base & rover, rover only, or base only configurations.
- Trimble® Inertial Platform™ technology for magnetically immune IMU-based tilt compensation.
- Partial Trimble ProPoint™ GNSS positioning engine for improved accuracy and productivity in challenging GNSS conditions.
- Trimble Maxwell™ 7 GNSS ASIC.
- 9 GB internal memory.
- Trimble xFill® correction outage technology.

- Supports Trimble CenterPoint® RTX corrections for RTK level accuracy worldwide via satellite/IP.
- Military-grade ultra-rugged design, IP68 rating.
- Optimized for Trimble Access<sup>™</sup> field software.

Find out more at: geospatial.trimble.com/R780



# **Trimble R780**







PERFORMANCE SPECIFICA	ATIONS	
GNSS TECHNOLOGY		
	Constellation agnostic, flexible signal tracking, improved measurement integration with Trimble ProPoint GNSS te Increased measurement and stakeout productivity and tompensation  Trimble RTX worldwide corrections  Advanced Trimble Maxwell 7 technology  Trimble EVEREST Plus™ multipath signal rejection  Spectrum Analyzer to troubleshoot GNSS jamming  Anti-spoofing capabilities  Japanese LTE Filtering below 1510 MHz allows antennas  Iridium Filtering above 1616 MHz allows the antenna to b	to be used 100 m away from Japanese LTE cell tower
SATELLITE TRACKING	000 110 110 (4 105 (100) 100 15	
	GPS: L1C, L1 C/A, L2E (L2P), L2C, L5 GLONASS: L1C/A, L1P. L2C/A, L2P, L3 Galileo: E1, E5A, E5B and E5AltBOC, E6 <sup>2</sup> BeiDou: B1, B2, B3, B1C, B2A QZSS: L1 C/A, L1C, L1S, L2C, L5, LEX/L6 IRNSS: L5 SBAS: L1 C/A (EGNOS/MSAS GAGAN/SDCM), L1 C/A ar L-Band: Trimble RTX	nd L5 (WAAS)
POSITIONING PERFORMAN	NCE <sup>3</sup>	
STATIC GNSS SURVEYING		
High-Precision Static		
	Horizontal	3 mm + 0.1 ppm RMS
	Vertical	3.5 mm + 0.4 ppm RMS
Static and Fast Static		
	Horizontal	3 mm + 0.5 ppm RMS
	Vertical	5 mm + 0.5 ppm RMS
REALTIME KINEMATIC SURVE	EYING	
Single Baseline < 30 km		
	Horizontal	8 mm + 1 ppm RMS
	Vertical	15 mm + 1 ppm RMS
Network RTK <sup>4</sup>		
	Horizontal	8 mm + 0.5 ppm RMS
	Vertical	15 mm + 0.5 ppm RMS
TDIMED 5 INSERTIAL BLATEORY	RTK start-up time for specified precisions <sup>5</sup>	2 to 8 seconds
TRIMBLE INERTIAL PLATFORM	VI (TIP) TECHNOLOGY	
TIP Compensated Surveying <sup>6</sup>	Harris and a	DTI/ + 0 + 0 F /0 ± 1± / + 2000 Dt 40
	Horizontal	RTK + 8 mm + 0.5 mm/° tilt (up to 30°) RMS
IMI I Integrity Manitor	Horizontal  Pias manitaring	RTX + 8 mm + 0.5 mm/° tilt (up to 30°) RMS
IMU Integrity Monitor TRIMBLE RTX CORRECTION S	Bias monitoring	Temperature, age and shock
CenterPoint RTX <sup>7</sup>	BERVICES	
Center-out KTA	Harizantal	2 cm RMS
	Horizontal  Vertical	5 cm RMS
	RTX convergence time for specified precisions in Trimble RTX Fast regions	<1min
	RTX convergence time for specified precisions in non RTX Fast regions	<3 min
TDIMDI F. FULL	RTX QuickStart convergence time for specified precisions	< 5 min
TRIMBLE xFILL <sup>8</sup>	Hadaaala	DTI/9 - 10 (win to DM)
	Horizontal	RTK9 + 10 mm/minute RMS
TDIMDLE VEH L DDENHUNAS	Vertical	RTK <sup>9</sup> + 20 mm/minute RMS
TRIMBLE xFILL PREMIUM <sup>8</sup>	Horizontal	3 cm RMS
	Vertical	7 cm RMS
	vortical	/ CITE (IVIO



# **Trimble R780**

**GNSS System** 





POSITIONING PERFORM.	ANCE <sup>3</sup> Cont.			
CODE DIFFERENTIAL GNSS POSITIONING				
	Horizontal	0.25 m + 1 ppm RMS		
	Vertical	0.50 m + 1 ppm RMS		
	SBAS <sup>10</sup>	Typically < 5 m 3DRMS		
HARDWARE				

HARDWARE			
PHYSICAL			
Dimensions (W×H)	13.9 cm x 13 cm (5.5 in x 5.1 in) including connectors		
Weight	1.55 kg (3.42 lb) receiver only including radio and battery		
Temperature <sup>11</sup>			
	Operating	-40 °C to +65 °C (-40 °F to +149 °F)	
	Storage	-40 °C to +75 °C (-40 °F to +167 °F)	
Humidity		100%, condensing	
Ingress protection		IP68 Certified per IEC-60529: waterproof/dustproof (1 m submersion for 1 hour)	
Shock and vibration			
	Pole drop	Designed to survive a 2 m (6.6 ft) pole drop onto concrete	
	Shock	Non-operating: 75 Gs at 6msec	
	Shock	Operating: 40 Gs at 10msec	
	Vibration	Mil-Std-810G, FIG 514.6E-1 Cat 24, Mil-Std-202G, FIG 214-1, Condition D	
ELECTRICAL			
	Internal	Rechargeable, removable Lithium-ion battery in internal battery compartment	
		Internal battery operates as a UPS during an ext power source failure	
		Internal battery will charge from external power source as long as source can support the power drain and is more than 11.8 VDC	
		Integrated charging circuitry	
	External	External power input with over-voltage protection on Port 1 (7-pin Lemo 2-key) Minimum 10.8 V, Maximum 28 VDC, shutdown optimized for 12 V lead acid battery operation	
		Power source supply (Internal/External) is hot-swap capable in the event of power source removal or cut off	
		DC external power input with over-voltage protection on Port 1 (Lemo)	
		Receiver automatically turns on when connected to external power	
	Power consumption	3.2 W in rover mode with internal receive radio <sup>12</sup>	
		5.2 W in base mode with internal 0.5 W transmit radio	
Operating times on internal battery <sup>13</sup>			
	Rover	5.5 hours; varies with temperature	
	Base station	5.5 hours; varies with temperature	
	450 MHz systems	Approximately 4 hours; varies with temperature	
	900 MHz systems	Approximately 4 hours; varies with temperature	

## COMMUNICATIONS AND DATA STORAGE

Lemo (Serial 1)	7-pin Lemo 2-key, Power Input, USB. Optional USB to RS232 serial cable. Receiver supports RNDIS communications over USB
Wi-Fi	Client or Access Point. Receive or transmit corrections. Wi-Fi b/g/n
Bluetooth® wireless technology	Fully-integrated sealed 2.4 GHz Bluetooth module
Integrated radios (optional)	Fully-integrated, fully-sealed internal 403-473 MHz; Internal 900 MHz; Rx/Tx
Channel spacing (450 MHz)	12.5 kHz or 25 kHz spacing available
Sensitivity (450 MHz)	-114 dBm (12 dB SINAD)
450 MHz output power	0.5 W, 2.0 W, depending on the local required licensing.
Frequency approvals (403–473 MHz)	Worldwide, depending on the local required licensing.
Positioning rates	1 Hz, 2 Hz, 5 Hz, 10 Hz, and 20 Hz
Data storage	9 GB internal data logging. Moving base and heading
Data format	CMR+, CMRx, RTCM 2.1, RTCM 2.3, RTCM 3.0, RTCM 3.1, RTCM 3.2 input and output 24 NMEA outputs, GSOF, RT17, and RT27 outputs



## Trimble R780

## **GNSS System**

## **CERTIFICATIONS** FCC Part 15 Subpart B (Class B Device), Part 15.247, Part 90 Canadian ICES-003 (Class B), RSS-GEN, RS-102, RSS-247 IEC62368-1 2nd Edition CISPR 32, EN 55032, EN55035 RCM mark, AS/CISPR 32, AS/NZS 4768 Japan MIC CE mark, Radio Equipment Directive (RED 2014/53/EU) RoHS compliance WEEE compliance

### TRIMBLE PROTECTED PROTECTION PLANS

Add a Trimble Protected protection plan for worry-free ownership over and above the standard Trimble product warranty. Added enhancements include coverage for wear & tear, environmental damage, and more. Accidental damage is covered with Premium plans, available only at point-of-sale in selected regions. For details, visit trimbleprotected.com or contact a local Trimble distributor

- Challenging GNSS environments are locations where the receiver has sufficient satellite availability to achieve Challenging GNSS environments are locations where the receiver has sufficient satellite availability to achieve minimum accuracy requirements, but where the signal may be partly obstructed by and/or reflected off of trees, buildings, and other objects. Actual results may vary based on user's geographic location and atmospheric activity, scintillation levels, GNSS constellation health and availability, and level of multipath and signal occlusion. The current capability in the receivers is based on publicly available information. As such, Trimble cannot guarantee that these receivers will be fully compatible with a future generation of Galileo satellites or signals. Precision and reliability may be subject to anomalies due to multipath, obstructions, satellite geometry, and atmospheric conditions. The specifications stated recommend the use of stable mounts in an open sky view, EMI and multipath clean environment, optimal GNSS constellation configurations, along with the use of survey practices that are geography account of the professional requirements and provided the application equivalent of the application equivalent or provided the properties of the application equivalent or provided the properties of the application equivalent or provided the properties that the provided the prov

- multipath clean environment, optimal GNSS constellation configurations, along with the use of survey practices that are generally accepted for performing the highest-order surveys for the applicable application including occupation times appropriate for baseline length. Baselines longer than 30 km require precise ephemeris and occupations up to 24 hours may be required to achieve the high precision static specification.

  Network RTK PPM values are referenced to the closest physical base station.

  May be affected by atmospheric conditions, signal multipath, obstructions and satellite geometry. Initialization reliability is continuously monitored to ensure highest quality.

  TIP references the overall positioning error estimate at the tip of the surveying pole throughout the tilt compensation range. RTK refers to the estimated horizontal precision of the underlying GNSS position, which is dependent on factors that affect GNSS solution quality. The 5 mm constant error component accounts for residual misalignment between the vertical axes of the receiver and the built-in Inertial Measurement Unit (IMU) after factory calibration, assuming the receiver is mounted on a standard 2 m carbon fiber range pole which is properly calibrated and free from physical defects. The tilt-dependent error component is a function of the quality of the computed tilt azimuth, which is assumed here to be aligned using optimal GNSS conditions. For best IMU tilt compensated results, perform a pole bias adjustment. a pole bias adjustment.
- RMS performance based on repeatable in field measurements. Achievable accuracy and initialization time may
- RMS performance based on repeatable in field measurements. Achievable accuracy and initialization time may vary based on type and capability of receiver and antenna, user's geographic location and atmospheric activity, scintillation levels, GNSS constellation health and availability and level of multipath including obstructions such as large trees and buildings.

  Accuracies are dependent on GNSS satellite availability, xFill positioning without an xFill Premium subscription ends after 5 minutes of radio downtime. xFill Premium will continue beyond 5 minutes providing the solution has converged, with typical precisions not exceeding 3 cm horizontal, 7 cm vertical. xFill is not available in all regions, check with your local sales representative for more information.

  RTK refers to the last reported precision before the correction source was lost and xFill started.

- 9. KTR refers to the last reported precision before the correction source was lost and xHIII started.
  10 Depends on SBAS system performance.
  11 Receiver will operate normally to -40 °C, internal batteries are rated from -20 °C to +60 °C (ambient +50 °C).
  12 Tracking GPS, GLONASS and SBAS satellites.
  13 Varies with temperature and wireless data rate. When using a receiver and internal radio in the transmit mode, it is recommended that an external 6 Ah or higher battery is used.

Specifications subject to change without notice













Contact your local Trimble Authorised Distribution Partner for more information

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